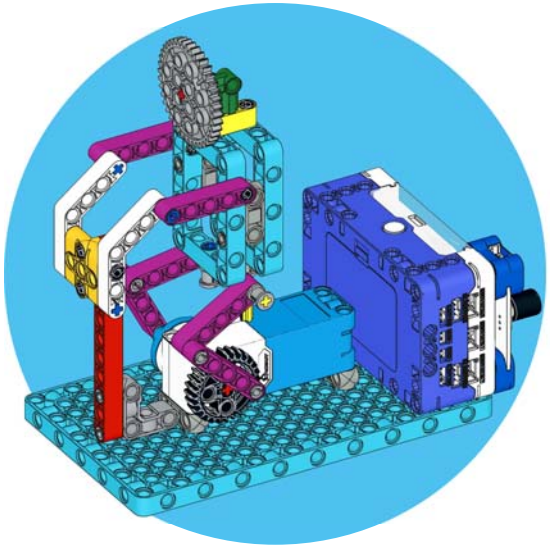
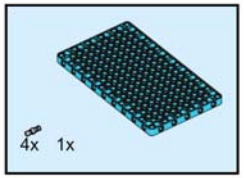
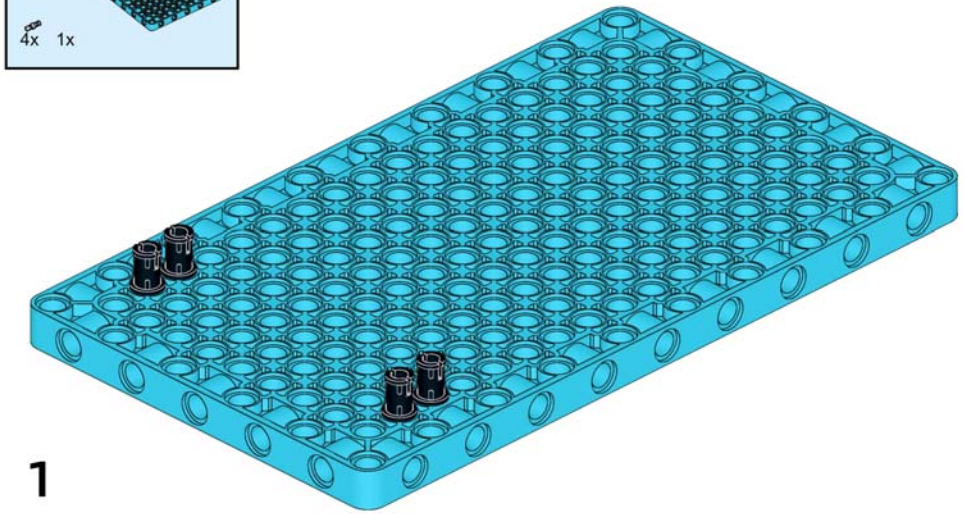
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Building Steps

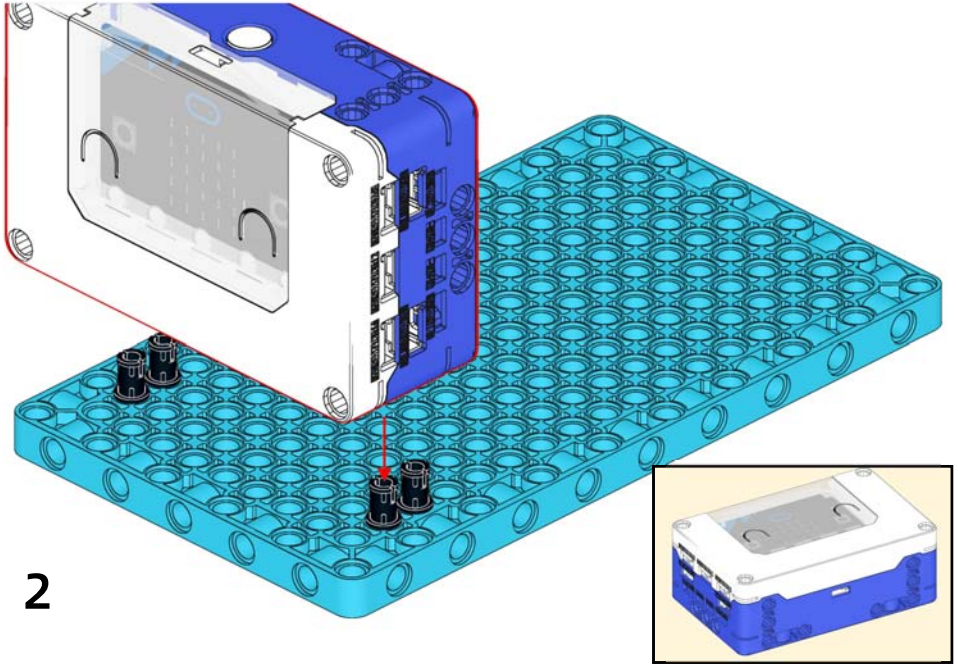


Spinning



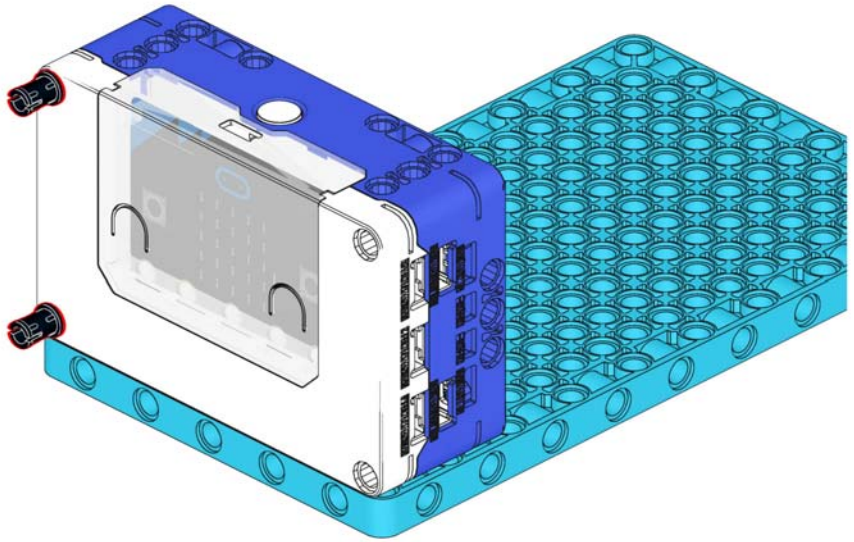


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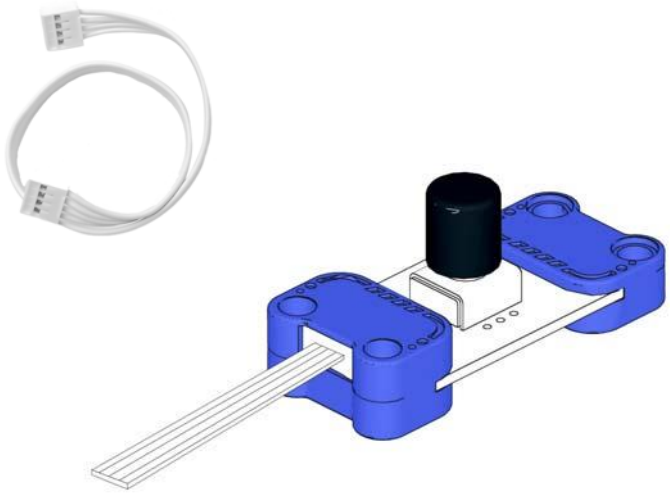
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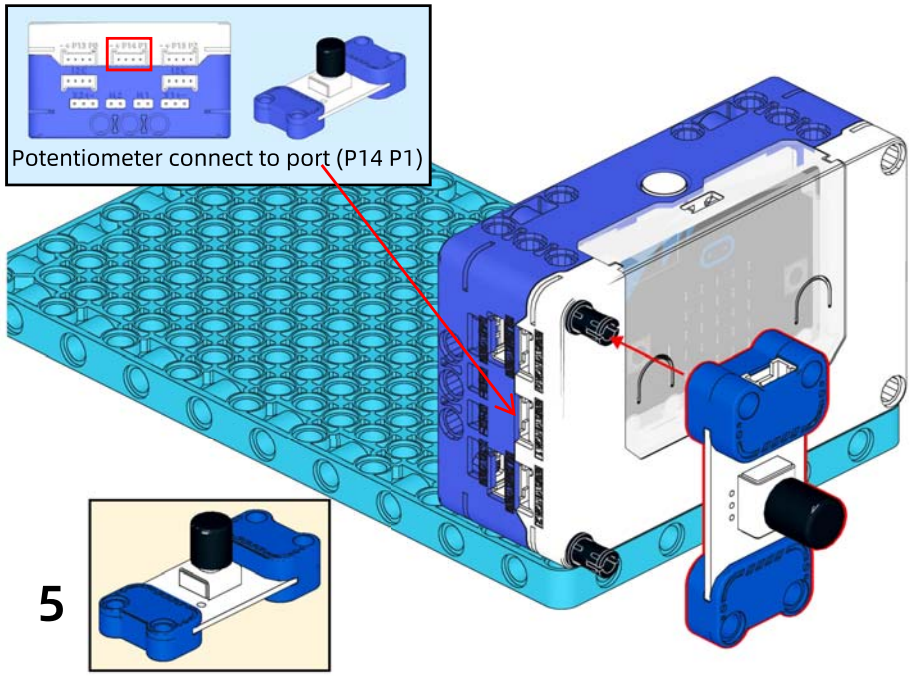


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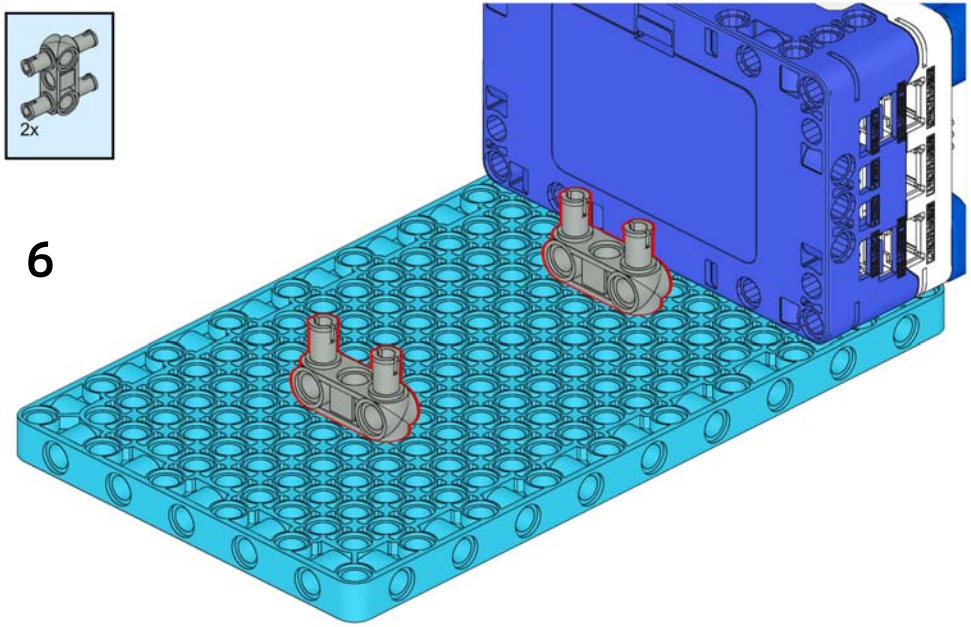


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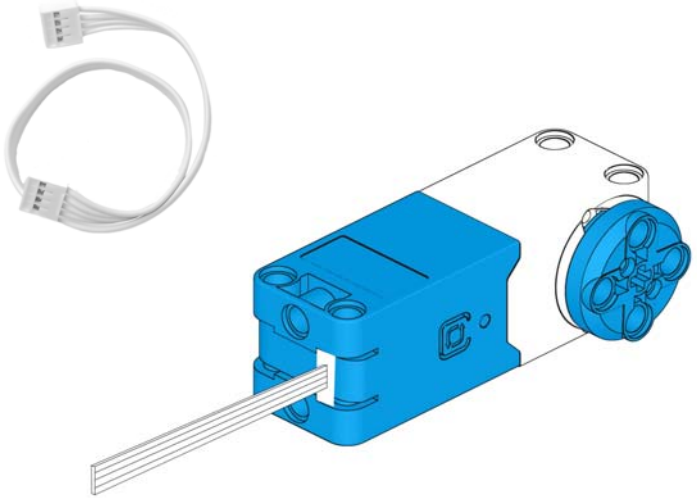


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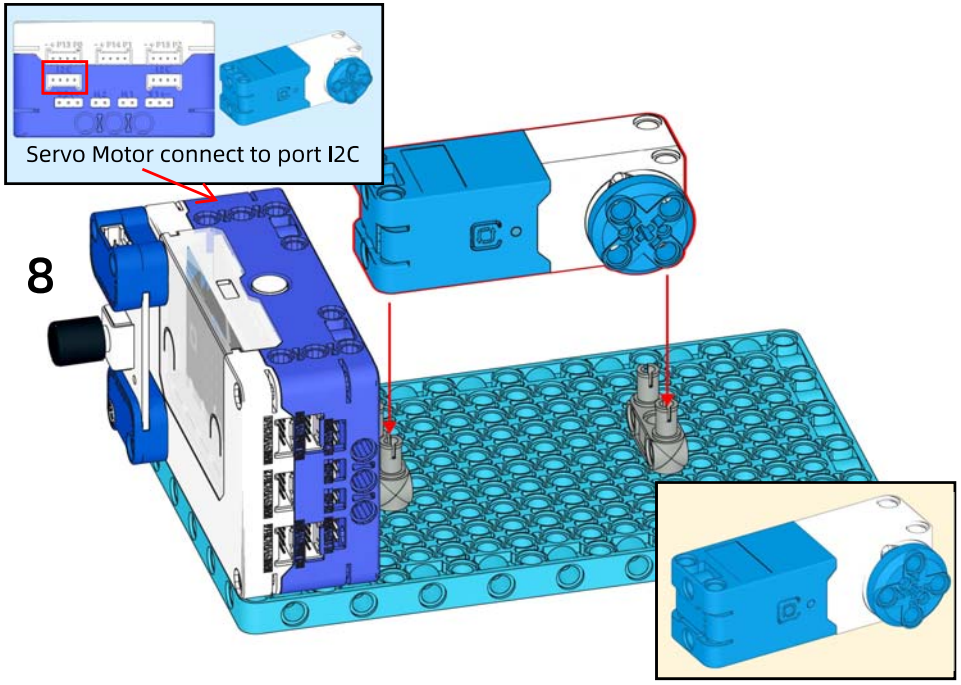
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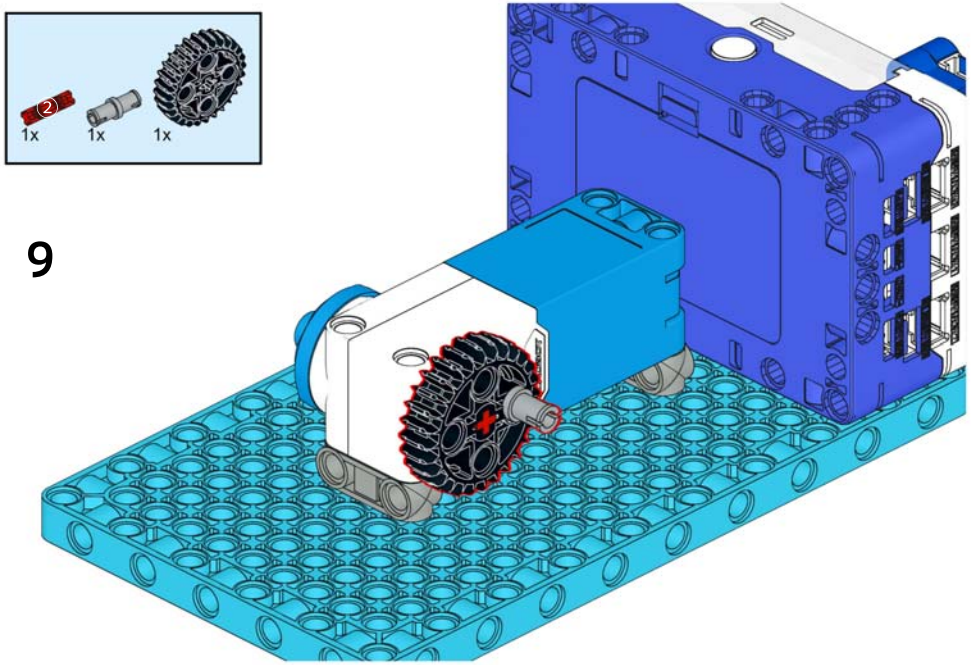


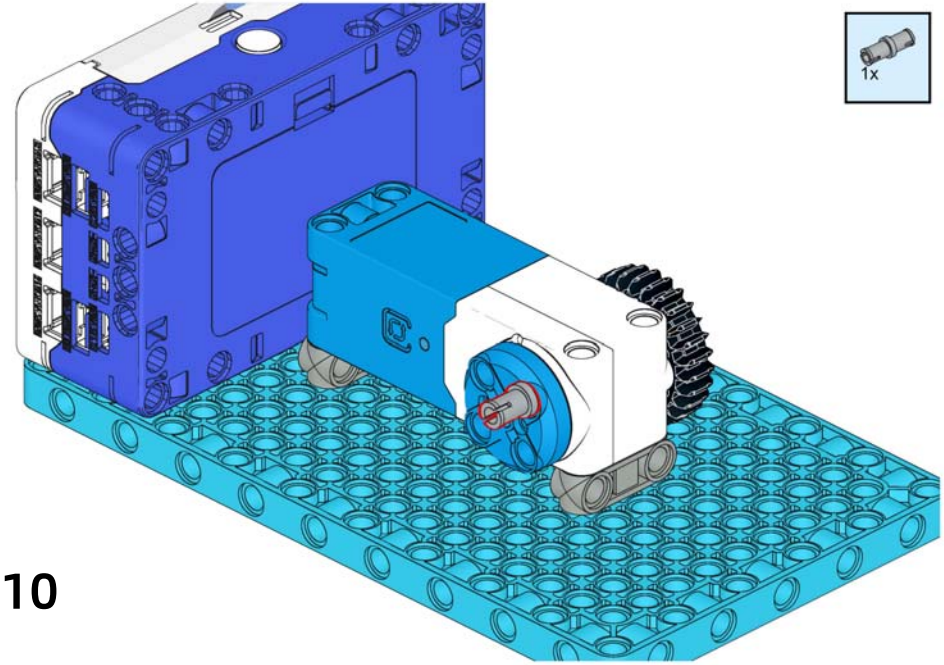
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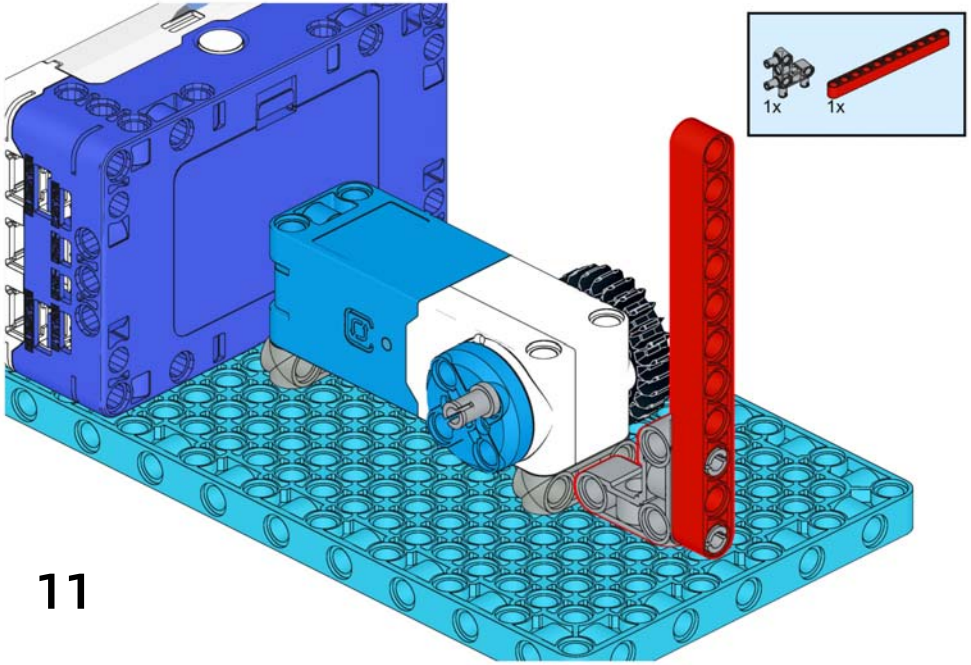


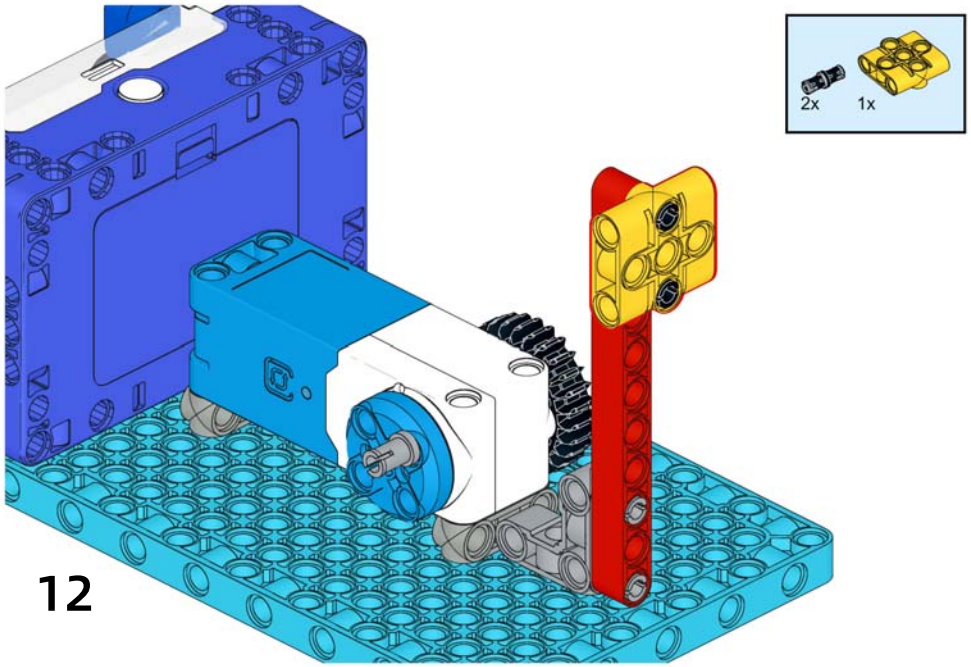
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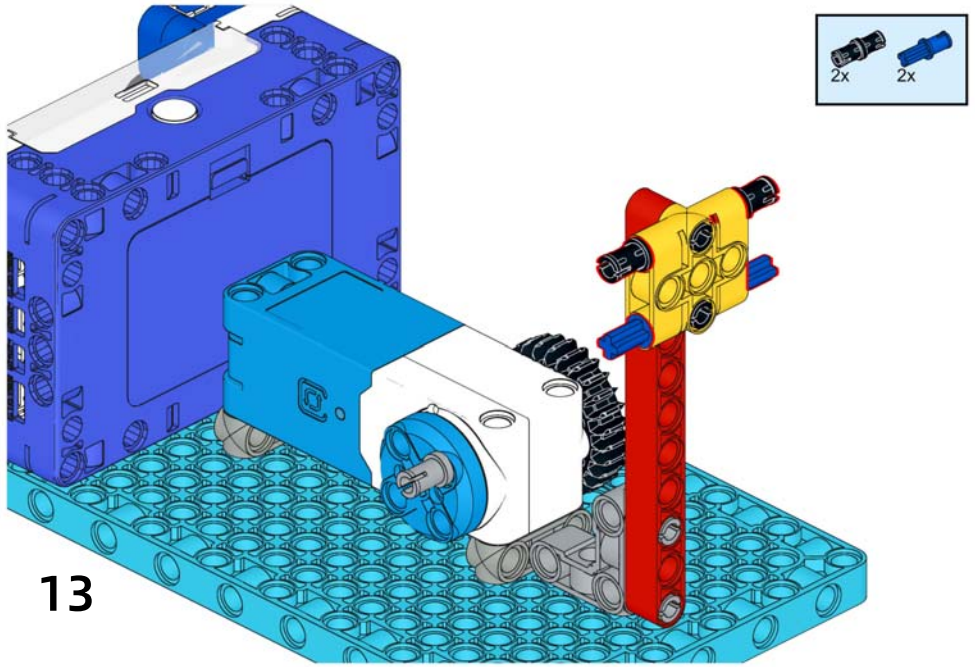

Servo Motor connect to port I2C
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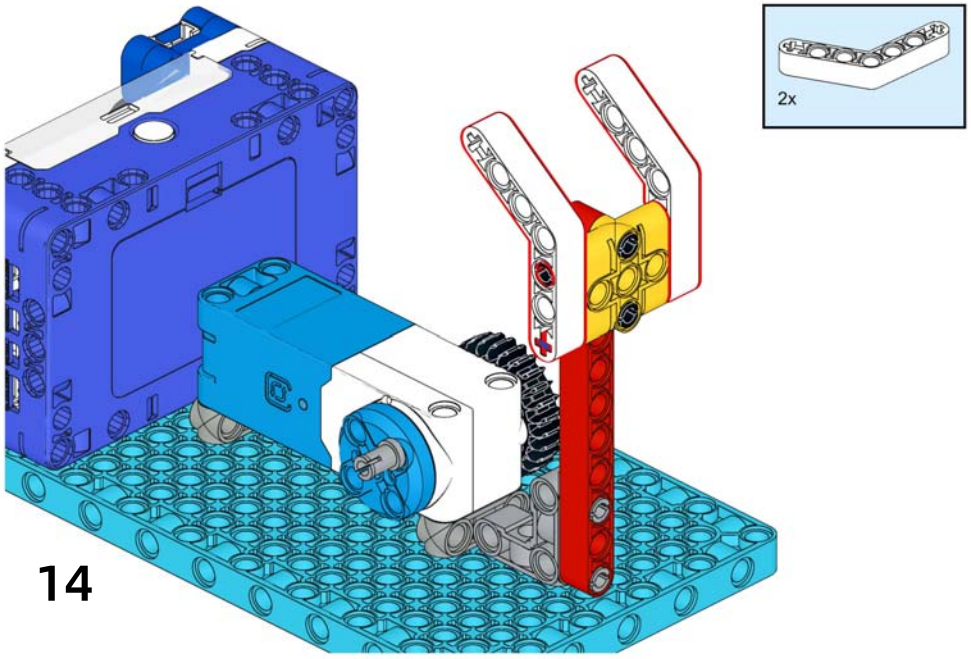

2
1x
1x
1x
9

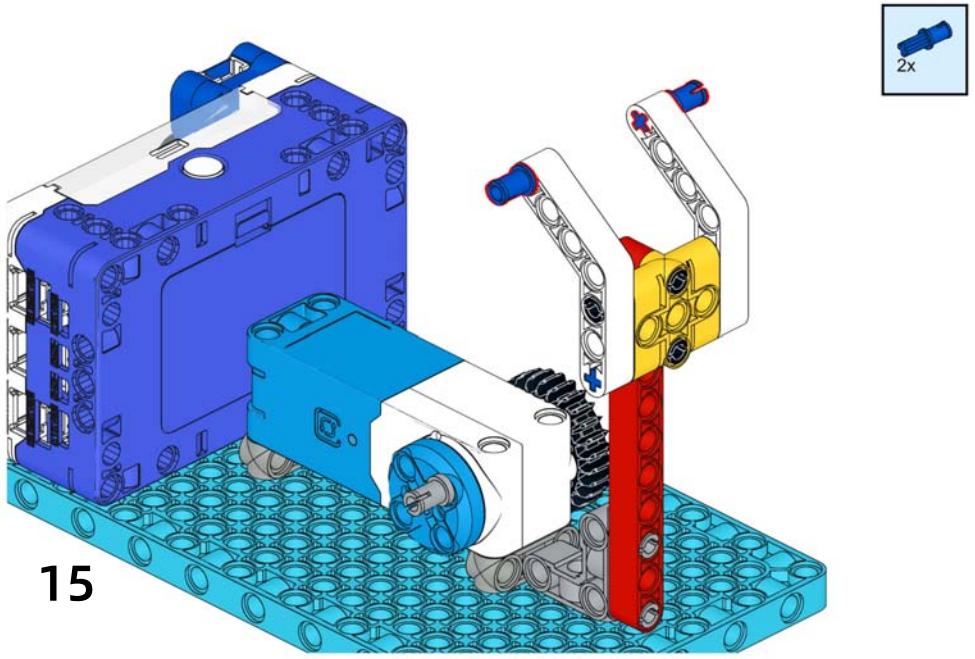

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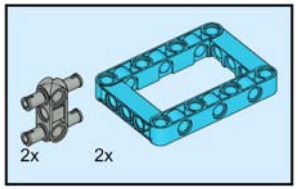

1x
1x
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2x
1x
12


2x
2x
13

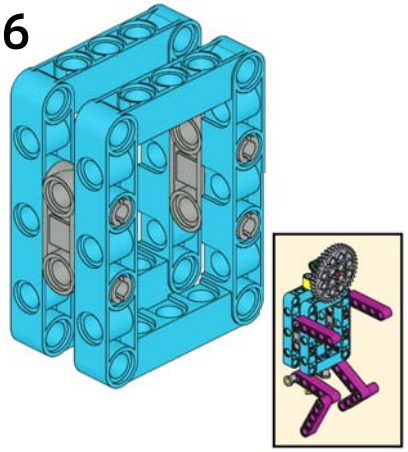

2x
14


2x
15

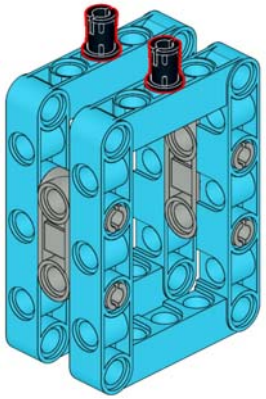


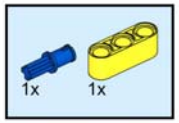


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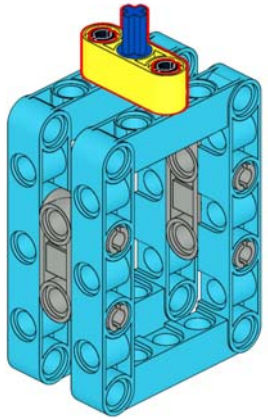


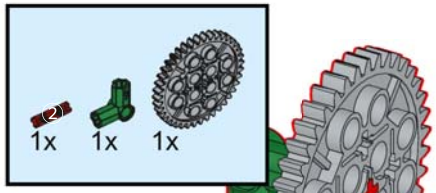
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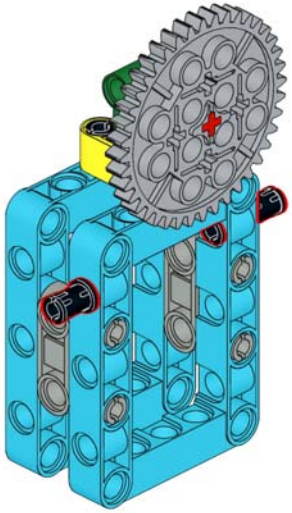


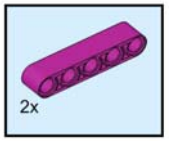


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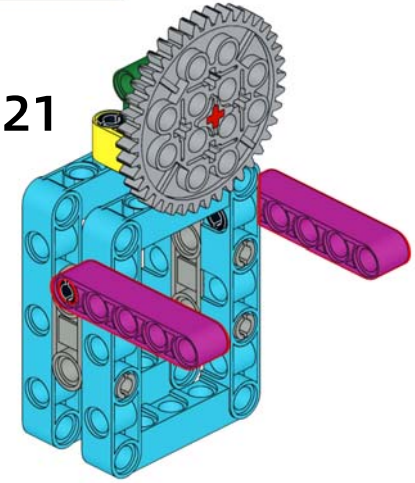


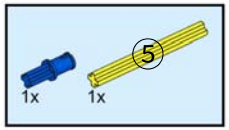
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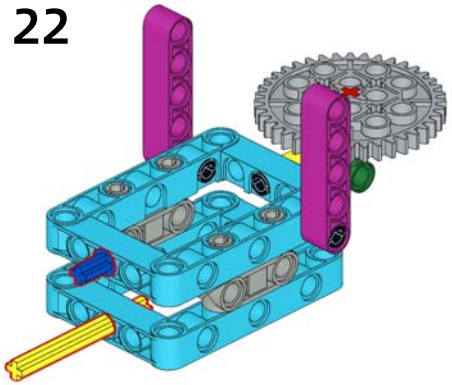


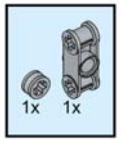
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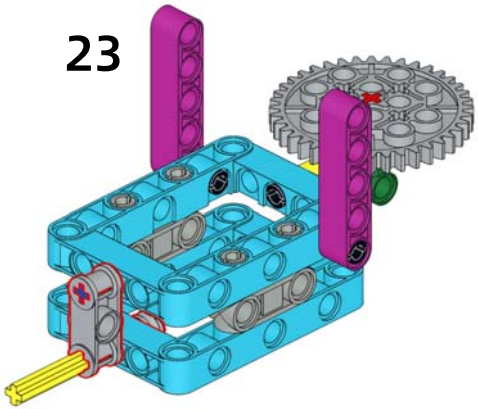


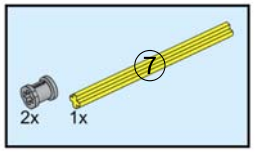
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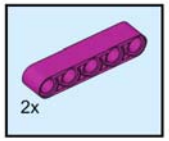




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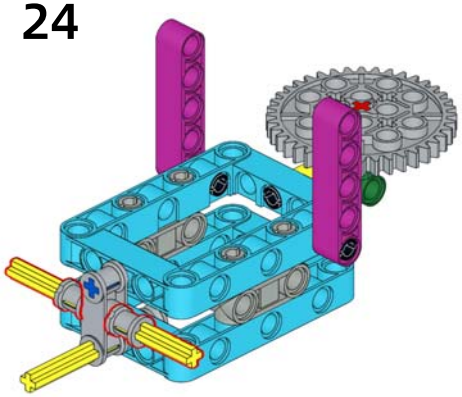




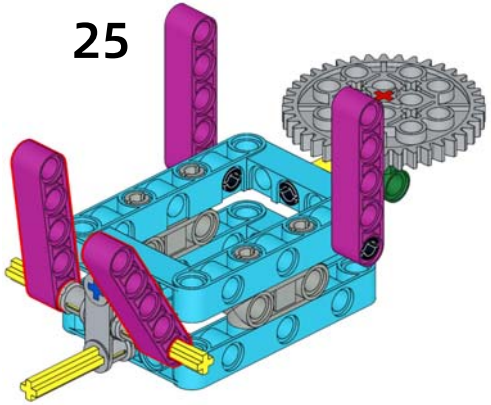




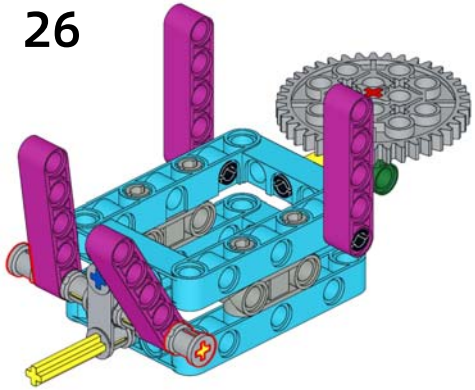
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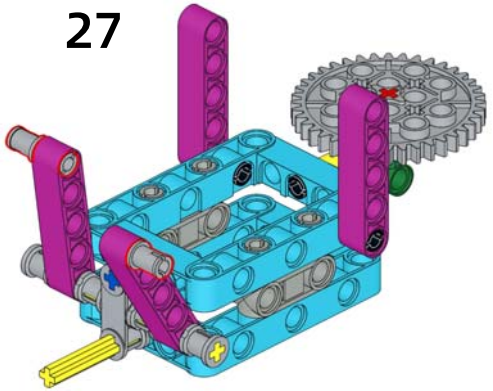
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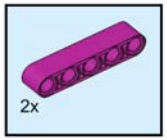


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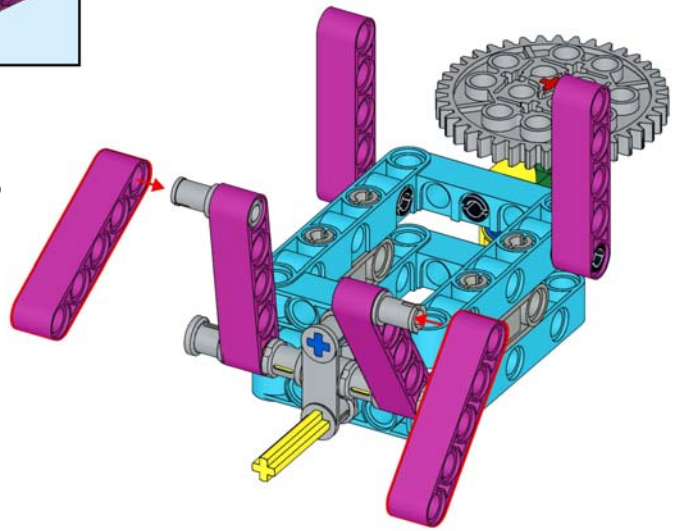


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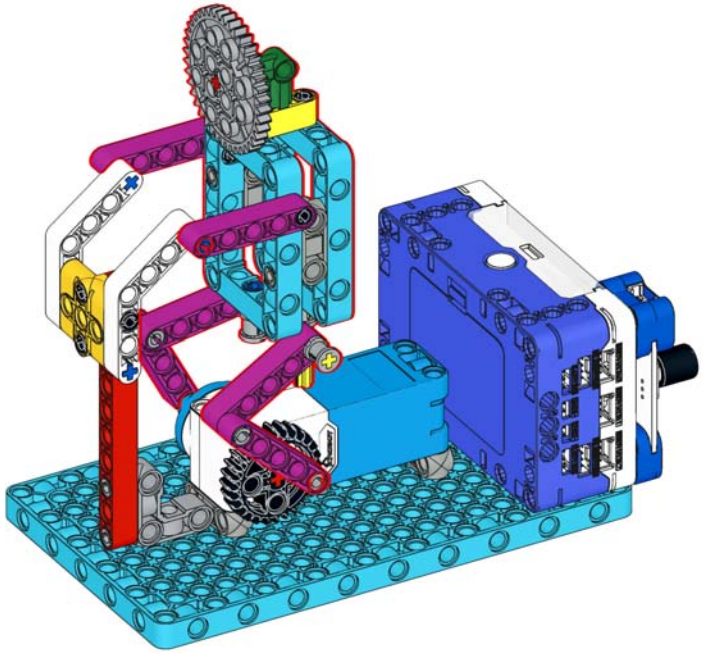




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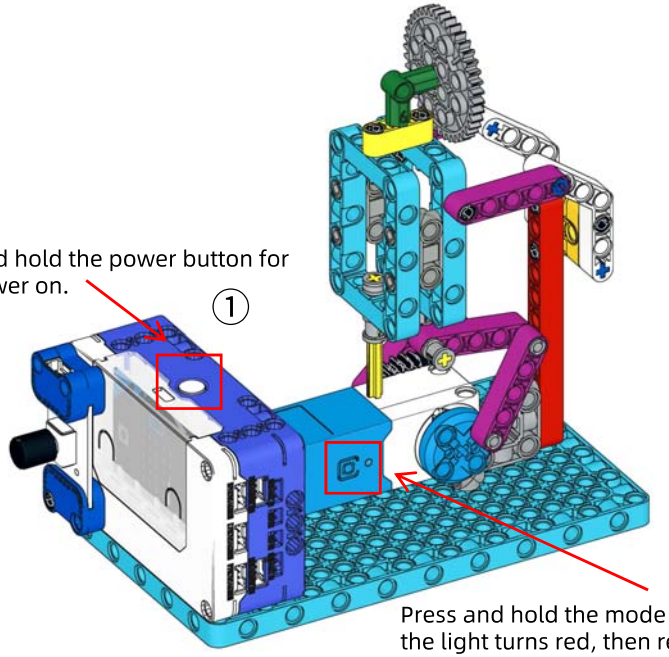


29



30

Press and hold the power button for 3s to power on.



Press and hold the mode button until the light turns red, then release.

31

