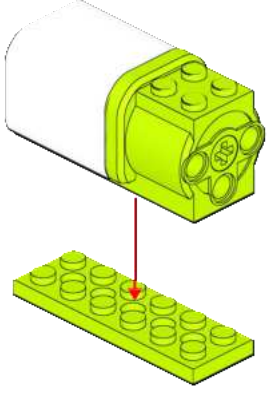
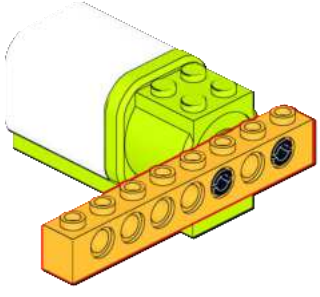
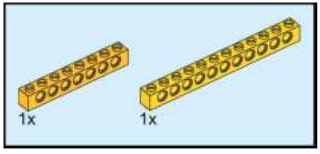
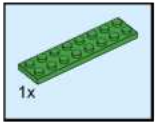


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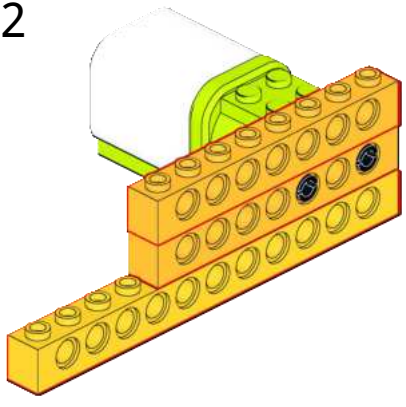


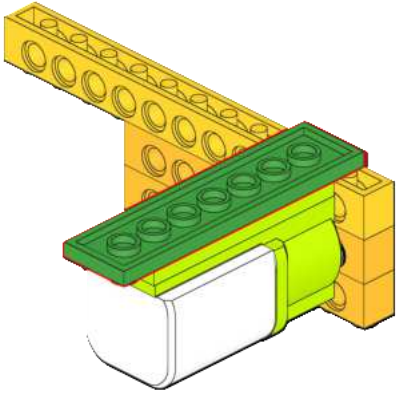




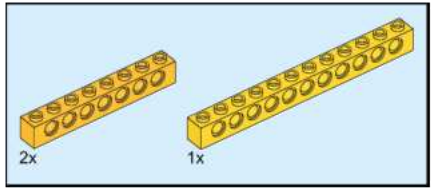


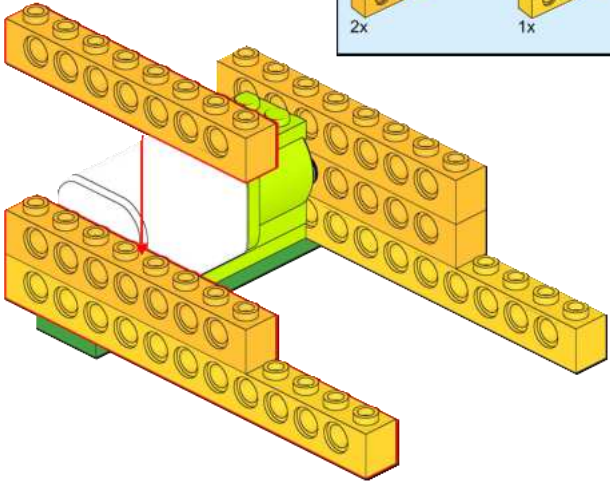
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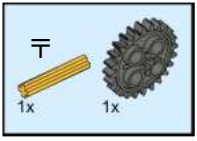




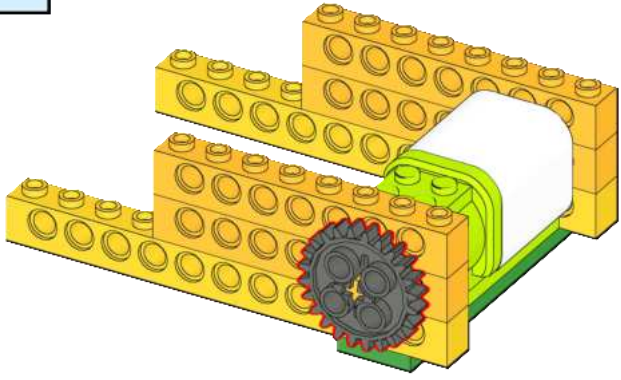
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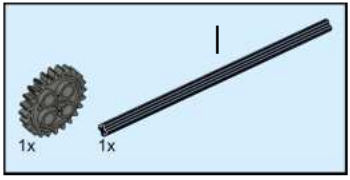




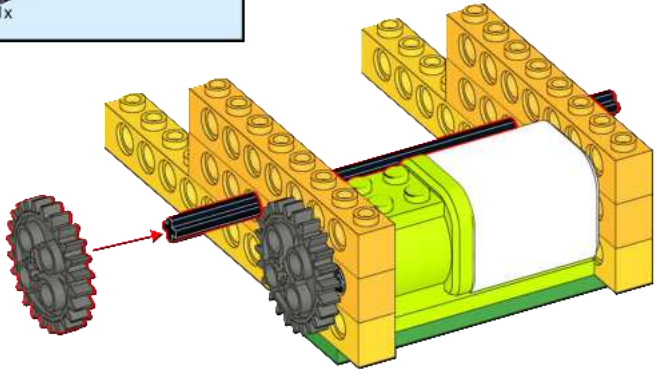


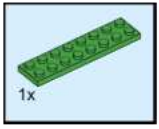
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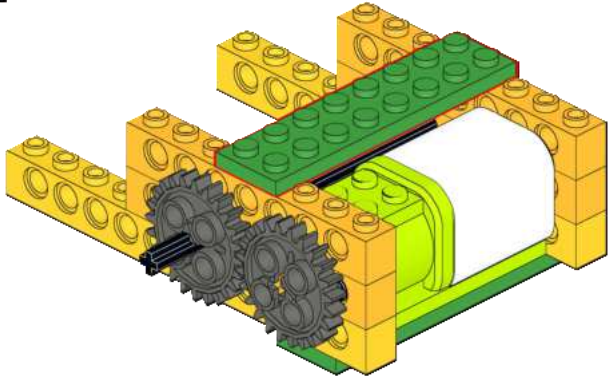


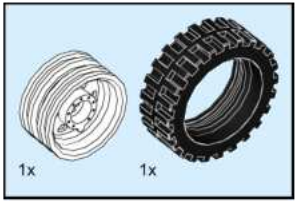
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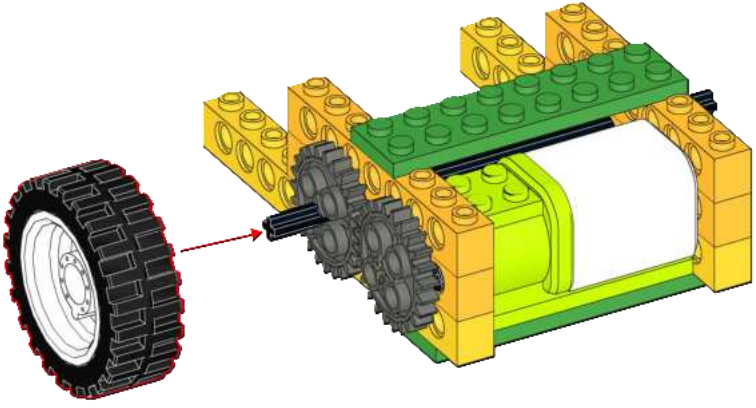


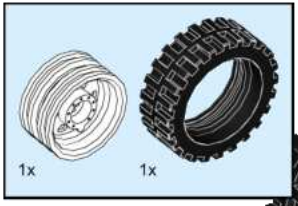


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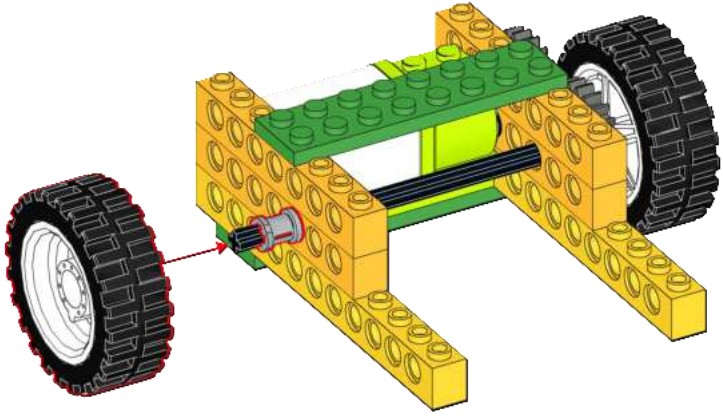
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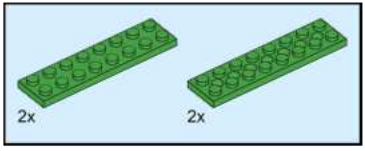




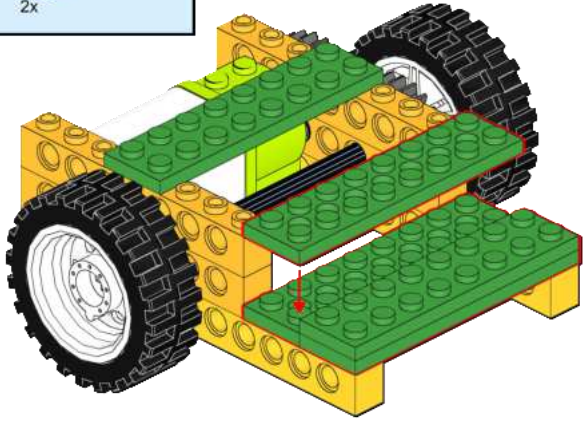


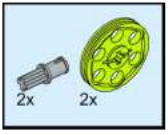
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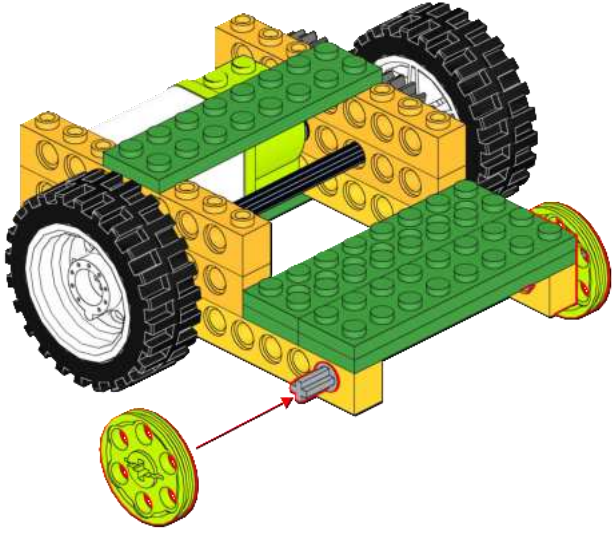


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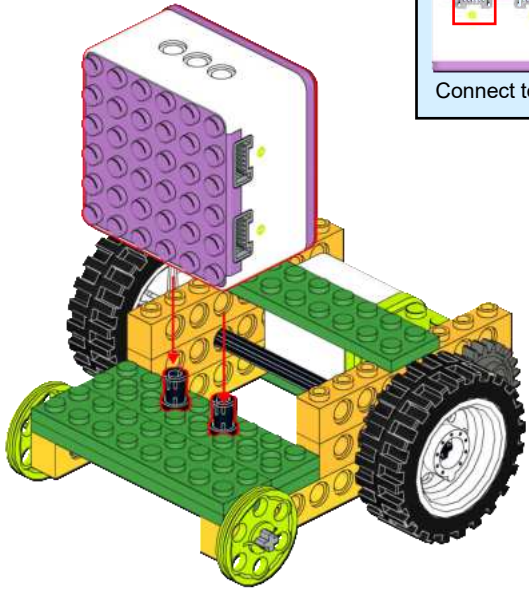


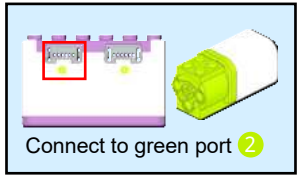
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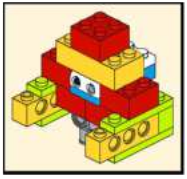


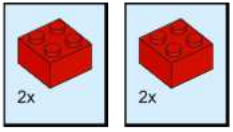


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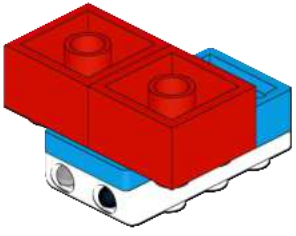


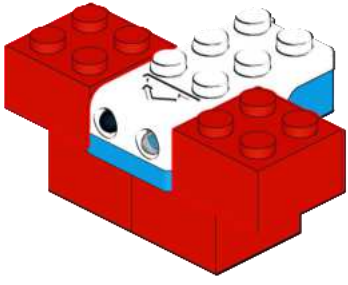


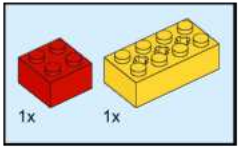


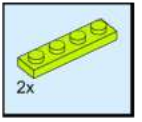


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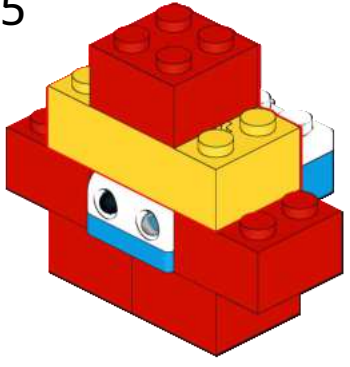


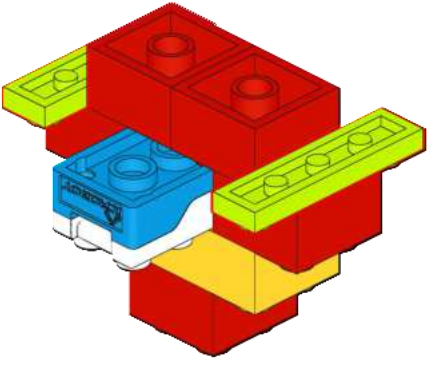


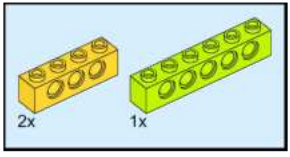




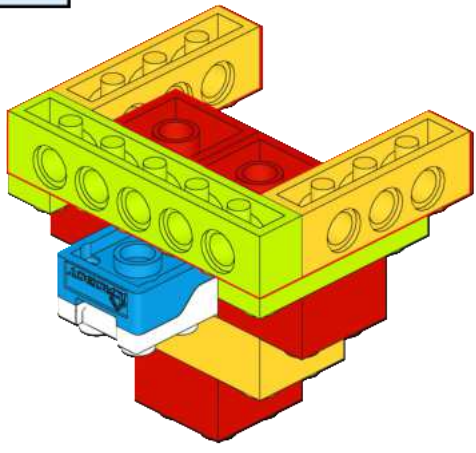
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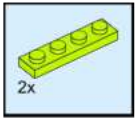


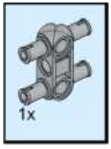




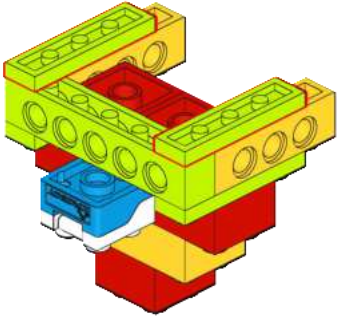
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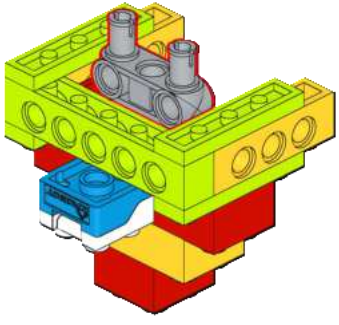




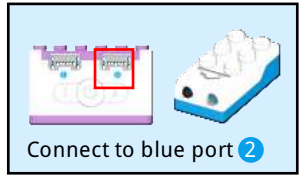


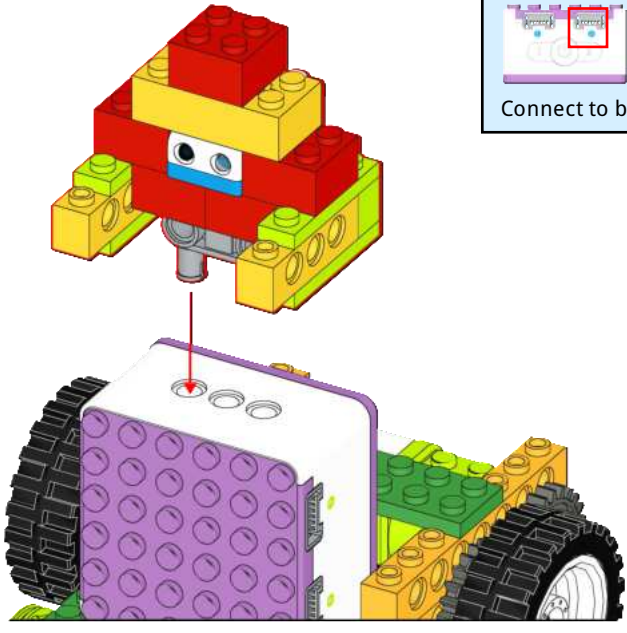
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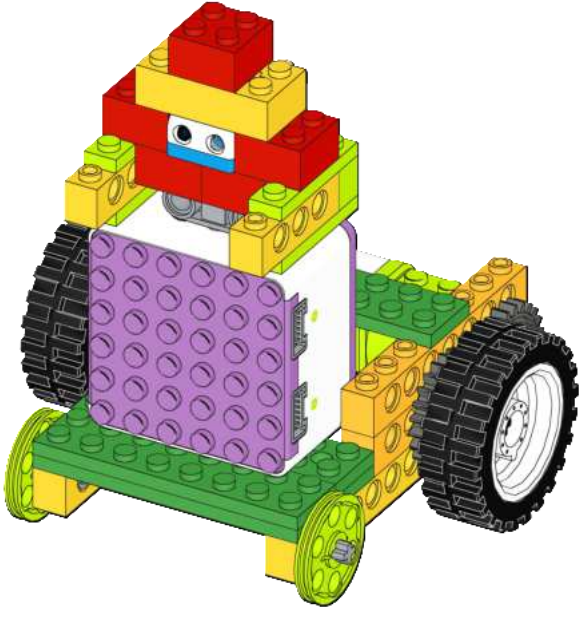


18





19



Ensure Bluetooth is Connected Properly



Object approaches the distance sensor, the robot stops,
and move away from the distance sensor, the robot goes forward.